

USER MANUAL

ZC-24DI

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Seneca Z-PC Line module: ZC-24DI

The ZC-24DI module acquires 24 single-ended digital signals, it converts them to a digital format (IN 1-24 state) and it counts the input-pulse number (pulse counter for IN 1-8).

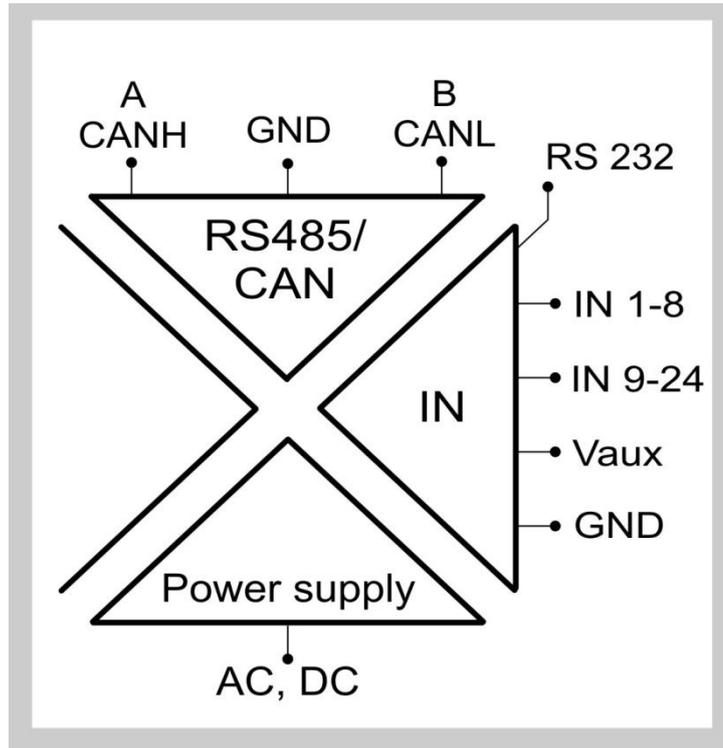
General characteristics

- Acquisition of digital signals from sensor: reed, NPN, PNP, proximity, contact, etc...
- Configuration of a filter applied to input signals IN1-IN8 (noise filter) to attenuate the noise overlapped to the digital signals
- Pulse counters for digital signals IN1-IN8, with max frequency equal to 10kHz, 32bit-registers
- Advanced management of the pulse counters for digital signals IN1-IN8 (for each pulse counter: overflow, preset value and reset/preset command are available)
- Power of 24 sensors using internal supply voltage (Vaux=16V)
- It is possible to configure the module (node) address and baud-rate by Dip-Switches
- It is possible to add/remove the module to/from RS485-bus without disconnecting the communication or power supply
- It is possible to switch automatically RS485 to RS232 or vice versa
- CAN interface with CANOpen protocol: max 1Mbps

Features

| INPUT | |
|--|--|
| Number | 24 |
| Type | Polarity (EN 61131 – 2 type 2): sink (pnp) |
| Equivalent low-pass-filter cut-off frequency | Configurable between: 16 Hz and 2.1kHz |
| Pulse min duration (ton) | 250µs |
| Sensor=off (input threshold) | The sensor is detected «off» if: acquired signal voltage between 0Vdc and 7 Vdc |
| Sensor=on (input threshold) | The sensor is detected «on» if: acquired signal voltage between 11Vdc and 30Vdc |
| Switching delay | Typical: 1.2ms; max: 3ms |
| Adsorbed current | 3mA (for each input) |
| Internal supply Vaux | The screw terminals 24-32 (Vaux) supply 16 V with reference to the screw terminal 7-15-23-31 (GND) |

| CONNECTIONS | |
|---------------------|--|
| RS485 interface | IDC10 connector for DIN 46277 rail (back-side panel) |
| 1500 Vac ISOLATIONS | |
| | Between: power supply, ModBUS RS485, digital inputs |



| POWER SUPPLY | |
|-------------------|---|
| Supply voltage | 10 – 40 Vdc or 19 – 28 Vac (50Hz - 60Hz) |
| Power consumption | Typical: 1.5W; Max: 2.5W |

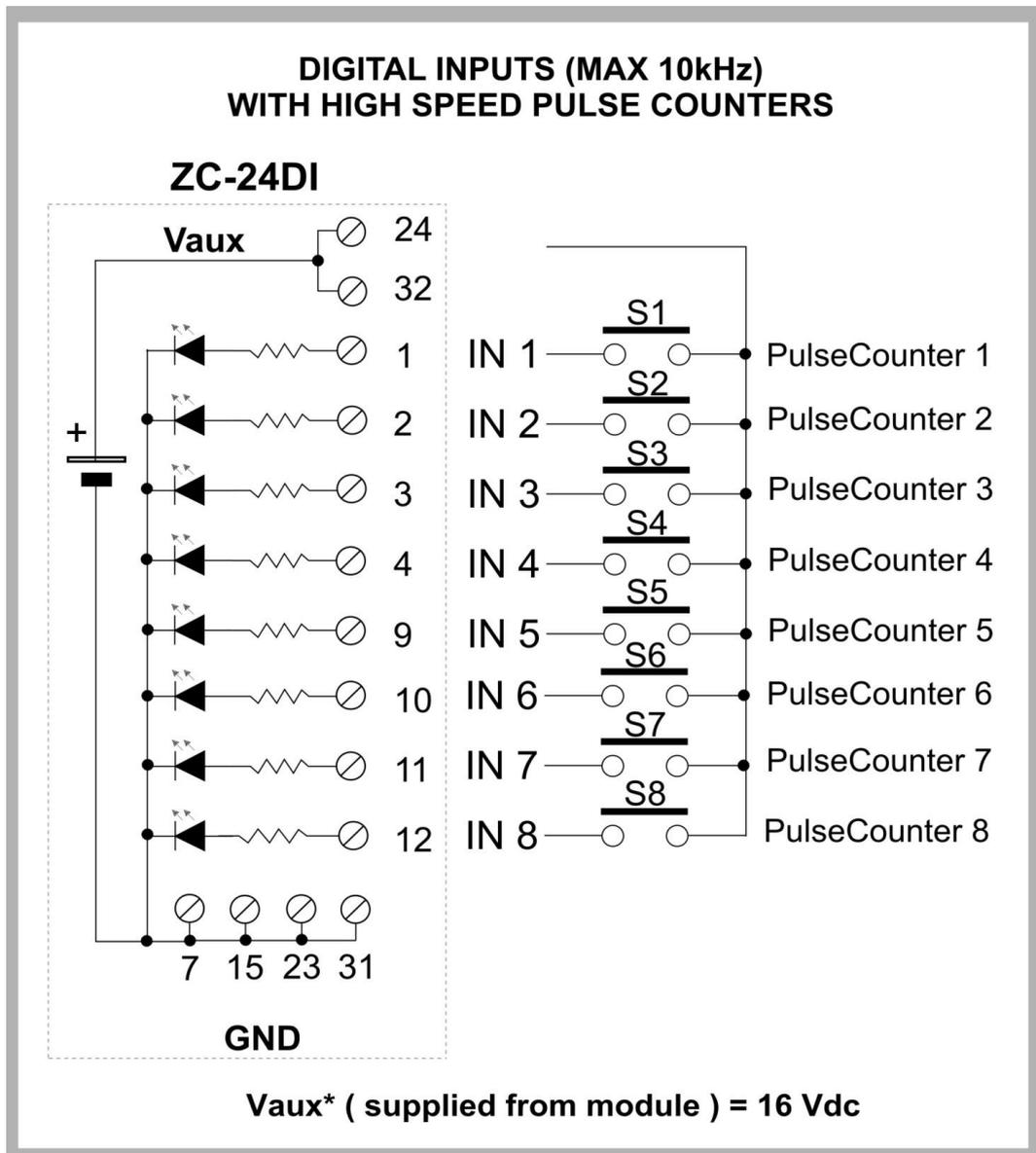
The power supply transformer necessary to supply the module must comply with EN60742 (Isolated transformers and safety transformers requirements). To protect the power supply, it is recommended to install a fuse.

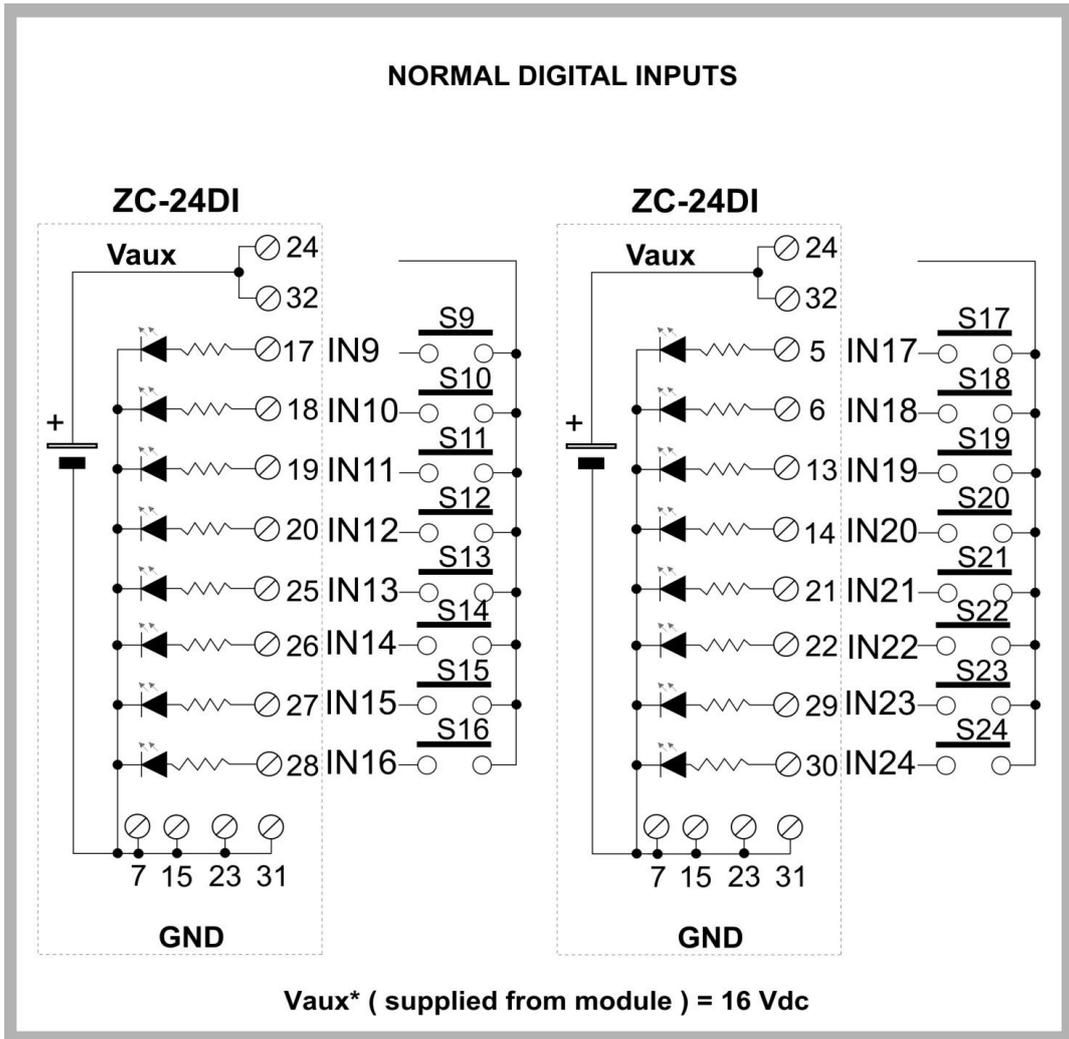
| MODULE CASE | |
|------------------|--|
| Case-type | PBT, black |
| Dimensions | Width W = 100 mm, Height H = 112mm, Depth D = 35 mm |
| Terminal board | Removable 4-way screw terminals: pitch 3.5mm, sections 2.5mm ² |
| Protection class | IP20 (International Protection) |

Input connections

Power on the module with < 40 Vdc or < 28 Vac voltage supply. These upper limits must not be exceeded to avoid serious damage to the module.

In the following figures are shown the connection of the sensors to the 24 inputs of ZC-24DI module. It's possible to connect to the module the sensors: Reed, NPN, PNP, Proximity, contact, etc... To power these sensors, connect each of them between the screw terminal 24 or 32 ($V_{aux}=16V$ with reference to the screw terminal 7, 15, 23 or 31 =GND) and one of the inputs IN1-24.





Dip-switches table

Power off the module before configuring it by Dip-Switches to avoid serious damage due to electrostatic discharges.



In the following tables: box without circle means Dip-Switch=0 (OFF state); box with circle means Dip-Switch=1 (ON state).

| BAUD-RATE (Dip-Switches: SW1) | | | | | | | |
|---|---------------------------|---------------------|---|---|---|----|---|
| 1 | 2 | 3 | Meaning | | | | |
| | | | Only Baud-Rate is acquired from memory(EEPROM) | | | | |
| | | ● | Baudrate=2400 | | | | |
| | ● | | Baudrate=4800 | | | | |
| | ● | ● | Baudrate=9600 | | | | |
| ● | | | Baudrate=19200 | | | | |
| ● | | ● | Baudrate=38400 | | | | |
| ● | ● | | Baudrate=57600 | | | | |
| ● | ● | ● | Baudrate=115200 | | | | |
| ADDRESS (Dip-Switches: SW1) | | | | | | | |
| 4 | 5 | 6 | 7 | 8 | 9 | 10 | Meaning |
| | | | | | | | Only address is acquired from memory(EEPROM) |
| | | | | | | ● | Address=1 |
| | | | | | ● | | Address=2 |
| | | | | | ● | ● | Address=3 |
| | | | | ● | | | Address=4 |
| | | | | ● | | ● | Address=5 |
| X | X | X | X | X | X | X | |
| ● | ● | ● | ● | ● | ● | ● | Address=127 |
| RS485 TERMINATOR (Dip-Switches: SW3) | | | | | | | |
| 1 | Meaning | | | | | | |
| | RS485 terminator disabled | | | | | | |
| ● | RS485 terminator enabled | | | | | | |
| COMMUNICATION PROTOCOL (Dip-Switch: SW2 and SW4) | | | | | | | |
| SW2 | SW4 | | | | | | |
| 1 | 1 | | | | | | |
| | | Protocol is ModBUS | | | | | |
| ● | ● | Protocol is CANOPEN | | | | | |

RS485 Register table

| Name | Range | Interpretation of register | R/W | Default | Address |
|--|--|----------------------------|-----|-------------------|-------------|
| MyType | / | MSB, LSB | R | | 40001 |
| | Id_Code (Module ID) | | | 0x20 (32 decimal) | Bit [15:8] |
| | Ext_Rev (Module version) | | | | Bit [7:0] |
| FWREV | / | Word | R | | 40002 |
| | Firmware Code | | | | |
| Errors | / | Bit | R | | 40006 |
| | These bits aren't used | | | / | Bit [15:8] |
| | Memory error (EEPROM): 0=there isn't; 1=there is | | | / | Bit 7 |
| | These bits aren't used | | | / | Bit [6:4] |
| | Over-temperature error: 0=there isn't; 1=there is | | | / | Bit 3 |
| | These bits aren't used | | | / | Bit [2:0] |
| Command | / | Word | R/W | | 40201 |
| <p>Reg.40201=0x5Cnn (preset counter values are loaded into pulse counters, using a bit interpretation to mask the inputs): load 40030,40031...40044,40045 into 40008, 40009...40022,40023. Examples: <u>0x5C01</u> allows to load PresetCounter1 into PulseCounter1 <u>0x5C02</u> allows to load PresetCounter2 into PulseCounter2 <u>0x5C03</u> allows to load PresetCounter1 into PulseCounter1 and PresetCounter2 into PulseCounter2 (not PresetCounter3 into PulseCounter3) and so on <u>0x5CFF</u> allows to load every PresetCounter into corresponding PulseCounter</p> | | | | | |
| <p>Reg.40201=0x5Dnn (pulse counters value are loaded with zero values, using a bit interpretation to mask the inputs) Examples: <u>0x5D01</u> allows to load PulseCounter1 with zero value <u>0x5D02</u> allows to load PulseCounter2 with zero value <u>0x5D03</u> allows to load PulseCounter1 and PresetCounter2 with zero value (not PresetCounter3 with zero value) and so on <u>0x5DFF</u> allows to load every PulseCounter with zero value</p> | | | | | |
| <p>Reg.40201=0x5Enn (counter overflows reset, using a bit interpretation to mask the inputs) Examples: <u>0x5E01</u> allows to reset PulseCounter1 overflow <u>0x5E02</u> allows to reset PulseCounter2 overflow <u>0x5E03</u> allows to reset PulseCounter2 overflow and to reset PulseCounter2 overflow (not to reset PulseCounter3 overflow) and so on <u>0x5EFF</u> allows to reset every PulseCounter overflow</p> | | | | | |
| Reg.40201=0x6BAC (the module writes the Dip-Switches-state in reg.40202) | | | | | |
| Reg.40201=0xBAB0 (save data in EEPROM memory) | | | | | |
| Reg.40201=0xC1A0 (module reset) | | | | | |
| Command aux | / | Bit | R | | 40202 |
| | These bits aren't used | | | / | Bit [15:10] |
| | Dip-Switches "SW1 [4:10]" state. They correspond to the module baud-rate | | | / | Bit [9:3] |
| | Dip-Switches "SW1 [1:3]" state. They correspond to the module address | | | / | Bit [2:0] |
| Filter [IN1-8] masked | / | Word | R/W | | 40024 |
| | These bits aren't used | | | / | Bit [15:8] |

| | | | | |
|-------------------------|---|------|------|------------|
| | Input [1..8] Filter enable Mask (only 0x00 or 0xFF allowed) 0x00 = Filter disabled (and Counters 1..8 Enabled) 0xFF = Filter enabled (and Counters 1..8 Disabled) | | 0xFF | Bit [7:0] |
| Filter [IN9-16] masked | / | Word | RO | 40025 |
| | These bits aren't used | | / | Bit [15:8] |
| | Filter activation for inputs IN9-IN16 using a bit interpretation to mask the inputs: are always deactivated | | 0x00 | Bit [7:0] |
| Filter [IN17-24] masked | / | Word | RO | 40026 |
| | These bits aren't used | | / | Bit [15:8] |
| | Filter activation for inputs IN17-IN24 using a bit interpretation to mask the inputs: are always deactivated | | 0x00 | Bit [7:0] |

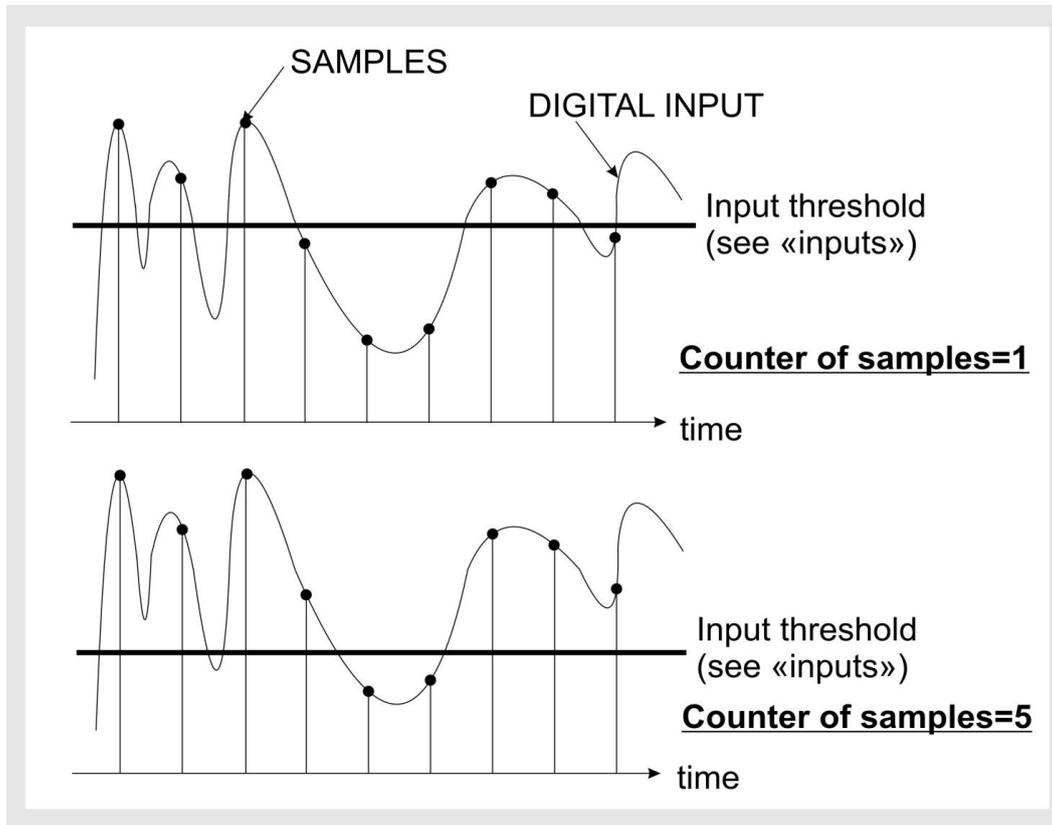
| | | | | | |
|--------------------------|-------------------------------|------|-----|-------------------|------------|
| Filter Number Of Samples | From 0 to 255 | Word | R/W | | 40027 |
| | These bits aren't used | | | | Bit [15:8] |
| | Number of samples for filter | | | 0x28 (40 decimal) | Bit [7:0] |
| Filter Sup | From 0 to 255 | Word | R/W | | 40028 |
| | These bits aren't used | | | | Bit [15:8] |
| | Inferior threshold for filter | | | 0x14 (20 decimal) | Bit [7:0] |
| Filter Inf | From 0 to 255 | Word | R/W | | 40029 |
| | These bits aren't used | | | | Bit [15:8] |
| | Superior threshold for filter | | | 0x14 (20 decimal) | Bit [7:0] |



Default equivalent filter value is 100Hz (cut-off frequency).

Filter functioning

Input filter operates in the following way: the ZC-24DI module samples the digital input with a frequency equal to 20kHz, and some samples are obtained (in the following figure there are 9 samples).



If counter of samples is greater than (or equal to) reg.40028 (Filter Sup), input signal is detected as "1".

If counter of samples is less than (or equal to) reg.40029 (Filter Inf), input signal is detected as "0".

If counter of samples is between reg.40029 (Filter Inf) and reg.40028 (Filter Sup), filter value is kept stored at the previous value.

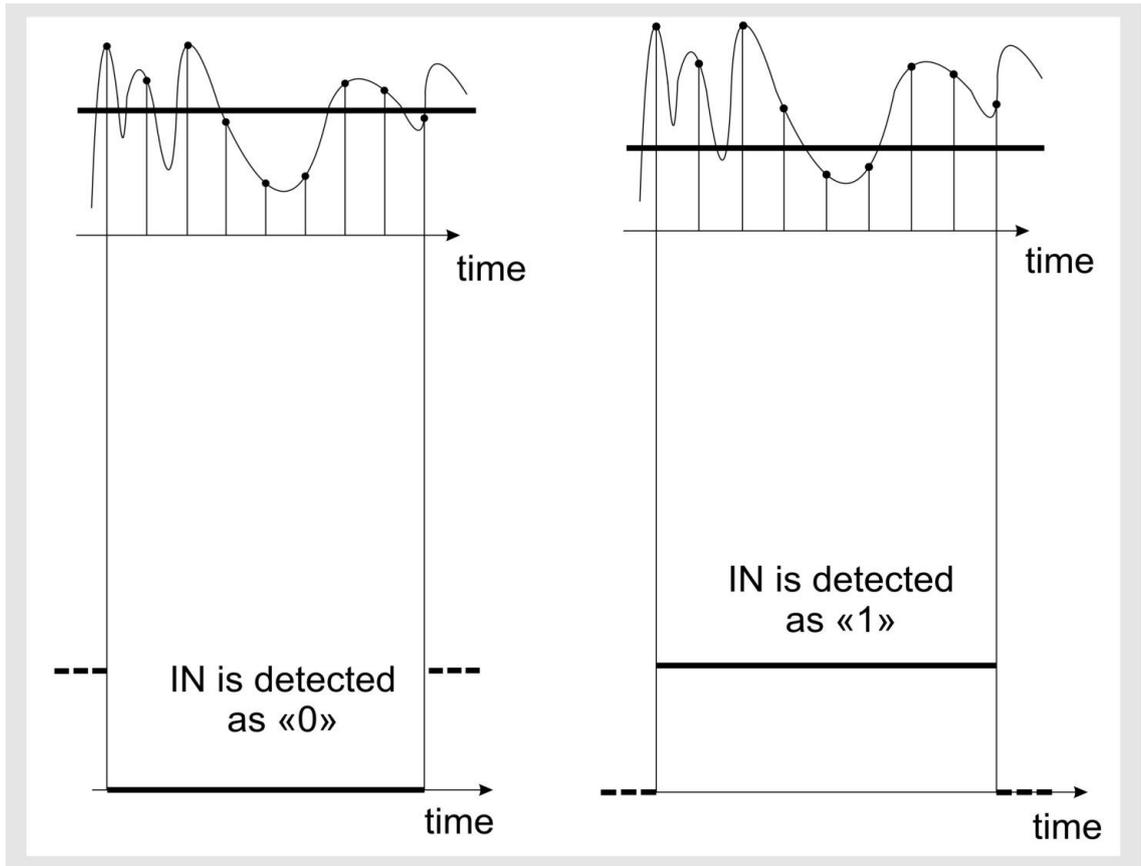
Example: with reference to the previous figure

A) Counter of samples (for superior figure)=0+1+1+1-1-1-1+1+1-1=1

If Filter Inf =2, Filter Sup=4: $1 \geq 4$ is false, $1 < 2$ is true. So input is detected as "0"

B) Counter of samples (for inferior figure)=0+1+1+1+1-1-1+1+1+1=5

If Filter Inf =2, Filter Sup=4: $5 \geq 4$ is true, $5 < 2$ is false. So input is detected as "1"



-  To deactivate the filter, write: `reg.40027=0x01, reg.40028=0x00, reg.40029=0x00.`
-  This filter action is described in configuration software as a low pass digital filter, with cut-off frequency from 16Hz to 2.1kHz.

| | | | | | |
|-----------------|---|----------|-----|-------|------------|
| Address Parity | Address: from 0x01=1 to 0xFF=255 | MSB, LSB | R/W | | 40048 |
| | Address for RS485 (address of module/node if parameters are configured by memory modality) | | | 1 | Bit [15:8] |
| | Parity for RS485: 0=no parity; 1=even; 2=odd | | | 0 | Bit [7:0] |
| Baudrate Delay | Delay: from 0x00=0 to 0xFF=255 | MSB, LSB | R/W | | 40049 |
| | Baud-rate for RS485 (baud-rate of module/node if parameters are configured by memory modality): 1=2400; 2=4800; 3=9600; 4=19200; 5=38400; 6=57600; 7=115200 | | | 38400 | Bit [15:8] |
| | Delay for RS485 (delay of communication response: pauses between the end of Rx message and the start of Tx message) | | | 0 | Bit [7:0] |
| State IN1-IN8 | | Bit | R | | 40003 |
| | These bits aren't used | | | / | Bit [15:8] |
| | IN8 state: 0=S8 open; 1=S8 closed | | | / | Bit 7 |
| | IN7 state: 0=S7 open; 1=S7 closed | | | / | Bit 6 |
| | IN6 state: 0=S6 open; 1=S6 closed | | | / | Bit 5 |
| | IN5 state: 0=S5 open; 1=S5 closed | | | / | Bit 4 |
| | IN4 state: 0=S4 open; 1=S4 closed | | | / | Bit 3 |
| | IN3 state: 0=S3 open; 1=S3 closed | | | / | Bit 2 |
| | IN2 state: 0=S2 open; 1=S2 closed | | | / | Bit 1 |
| | IN1 state: 0=S1 open; 1=S1 closed | | | / | Bit 0 |
| State IN9-IN16 | | Bit | R | | 40004 |
| | These bits aren't used | | | / | Bit [15:8] |
| | IN16 state: 0=S16 open; 1=S16 closed | | | / | Bit 7 |
| | IN15 state: 0=S15 open; 1=S15 closed | | | / | Bit 6 |
| | IN14 state: 0=S14 open; 1=S14 closed | | | / | Bit 5 |
| | IN13 state: 0=S13 open; 1=S13 closed | | | / | Bit 4 |
| | IN12 state: 0=S12 open; 1=S12 closed | | | / | Bit 3 |
| | IN11 state: 0=S11 open; 1=S11 closed | | | / | Bit 2 |
| | IN10 state: 0=S10 open; 1=S10 closed | | | / | Bit 1 |
| | IN9 state: 0=S9 open; 1=S9 closed | | | / | Bit 0 |
| State IN17-IN24 | | Bit | R | | 40005 |
| | These bits aren't used | | | / | Bit [15:8] |
| | IN24 state: 0=S24 open; 1=S24 closed | | | / | Bit 7 |
| | IN23 state: 0=S23 open; 1=S23 closed | | | / | Bit 6 |
| | IN22 state: 0=S22 open; 1=S22 closed | | | / | Bit 5 |
| | IN21 state: 0=S21 open; 1=S21 closed | | | / | Bit 4 |
| | IN20 state: 0=S20 open; 1=S20 closed | | | / | Bit 3 |
| | IN17 state: 0=S19 open; 1=S19 closed | | | / | Bit 2 |
| | IN18 state: 0=S18 open; 1=S18 closed | | | / | Bit 1 |
| | IN17 state: 0=S17 open; 1=S17 closed | | | / | Bit 0 |
| State IN1-IN16 | | Bit | R | | 40301 |
| | IN16 state: 0=S16 open; 1=S16 closed | | | / | Bit 15 |
| | IN15 state: 0=S15 open; 1=S15 closed | | | / | Bit 14 |
| | IN14 state: 0=S14 open; 1=S14 closed | | | / | Bit 13 |
| | IN13 state: 0=S13 open; 1=S13 closed | | | / | Bit 12 |
| | IN12 state: 0=S12 open; 1=S12 closed | | | / | Bit 11 |
| | IN11 state: 0=S11 open; 1=S11 closed | | | / | Bit 10 |
| | IN10 state: 0=S10 open; 1=S10 closed | | | / | Bit 9 |
| | IN9 state: 0=S9 open; 1=S9 closed | | | / | Bit 8 |
| | IN8 state: 0=S8 open; 1=S8 closed | | | / | Bit 7 |
| | IN7 state: 0=S7 open; 1=S7 closed | | | / | Bit 6 |
| | IN6 state: 0=S6 open; 1=S6 closed | | | / | Bit 5 |

| | | | |
|-----------------|--------------------------------------|-----|------------|
| | IN5 state: 0=S5 open; 1=S5 closed | / | Bit 4 |
| | IN4 state: 0=S4 open; 1=S4 closed | / | Bit 3 |
| | IN3 state: 0=S3 open; 1=S3 closed | / | Bit 2 |
| | IN2 state: 0=S2 open; 1=S2 closed | / | Bit 1 |
| | IN1 state: 0=S1 open; 1=S1 closed | / | Bit 0 |
| State IN17-IN24 | | Bit | R |
| | These bits aren't used | / | Bit [15:8] |
| | IN24 state: 0=S24 open; 1=S24 closed | / | Bit 7 |
| | IN23 state: 0=S23 open; 1=S23 closed | / | Bit 6 |
| | IN22 state: 0=S22 open; 1=S22 closed | / | Bit 5 |
| | IN21 state: 0=S21 open; 1=S21 closed | / | Bit 4 |
| | IN20 state: 0=S20 open; 1=S20 closed | / | Bit 3 |
| | IN19 state: 0=S19 open; 1=S19 closed | / | Bit 2 |
| | IN18 state: 0=S18 open; 1=S18 closed | / | Bit 1 |
| | IN17 state: 0=S17 open; 1=S17 closed | / | Bit 0 |

| | | | | | |
|--------------------|---------------------------------------|-------------|-----|--|-------|
| PulseCounter1_MSW | Between:0; (2^31)-1 | FP32bit-MSW | R | | 40008 |
| PulseCounter1_LSW | | FP32bit-LSW | R | | 40009 |
| | 32-bit pulse counter for input 1 | | | | |
| PresetCounter1_MSW | Between:0; (2^31)-1 | FP32bit-MSW | R/W | | 40030 |
| PresetCounter1_LSW | | FP32bit-LSW | R/W | | 40031 |
| | Preset counter value of PulseCounter1 | | | | |
| PulseCounter2_MSW | Between:0; (2^31)-1 | FP32bit-MSW | R | | 40010 |
| PulseCounter2_LSW | | FP32bit-LSW | R | | 40011 |
| | 32-bit pulse counter for input 2 | | | | |
| PresetCounter2_MSW | Between:0; (2^31)-1 | FP32bit-MSW | R/W | | 40032 |
| PresetCounter2_LSW | | FP32bit-LSW | R/W | | 40033 |
| | Preset counter value of PulseCounter2 | | | | |
| PulseCounter3_MSW | Between:0; (2^31)-1 | FP32bit-MSW | R | | 40012 |
| PulseCounter3_LSW | | FP32bit-LSW | R | | 40013 |
| | 32-bit pulse counter for input 3 | | | | |
| PresetCounter3_MSW | Between:0; (2^31)-1 | FP32bit-MSW | R/W | | 40034 |
| PresetCounter3_LSW | | FP32bit-LSW | R/W | | 40035 |
| | Preset counter value of PulseCounter3 | | | | |
| PulseCounter4_MSW | Between:0; (2^31)-1 | FP32bit-MSW | R | | 40014 |
| PulseCounter4_LSW | | FP32bit-LSW | R | | 40015 |
| | 32-bit pulse counter for input 4 | | | | |
| PresetCounter4_MSW | Between:0; (2^31)-1 | FP32bit-MSW | R/W | | 40036 |
| PresetCounter4_LSW | | FP32bit-LSW | R/W | | 40037 |
| | Preset counter value of PulseCounter4 | | | | |

| | | | | | |
|--------------------|---|-------------|-----|---|-------|
| PulseCounter5_MSW | Between:0; (2 ³¹)-1 | FP32bit-MSW | R | | 40016 |
| PulseCounter5_LSW | | FP32bit-LSW | R | | 40017 |
| | 32-bit pulse counter for input 5 | | | | |
| PresetCounter5_MSW | Between:0; (2 ³¹)-1 | FP32bit-MSW | R/W | | 40038 |
| PresetCounter5_LSW | | FP32bit-LSW | R/W | | 40039 |
| | Preset counter value of PulseCounter5 | | | | |
| PulseCounter6_MSW | Between:0; (2 ³¹)-1 | FP32bit-MSW | R | | 40018 |
| PulseCounter6_LSW | | FP32bit-LSW | R | | 40019 |
| | 32-bit pulse counter for input 6 | | | | |
| PresetCounter6_MSW | Between:0; (2 ³¹)-1 | FP32bit-MSW | R/W | | 40040 |
| PresetCounter6_LSW | | FP32bit-LSW | R/W | | 40041 |
| | Preset counter value of PulseCounter6 | | | | |
| PulseCounter7_MSW | Between:0; (2 ³¹)-1 | FP32bit-MSW | R | | 40020 |
| PulseCounter7_LSW | | FP32bit-LSW | R | | 40021 |
| | 32-bit pulse counter for input 7 | | | | |
| PresetCounter7_MSW | Between:0; (2 ³¹)-1 | FP32bit-MSW | R/W | | 40042 |
| PresetCounter7_LSW | | FP32bit-LSW | R/W | | 40043 |
| | Preset counter value of PulseCounter7 | | | | |
| PulseCounter8_MSW | Between:0; (2 ³¹)-1 | FP32bit-MSW | R | | 40022 |
| PulseCounter8_LSW | | FP32bit-LSW | R | | 40023 |
| | 32-bit pulse counter for input 8 | | | | |
| PresetCounter8_MSW | Between:0; (2 ³¹)-1 | FP32bit-MSW | R/W | | 40044 |
| PresetCounter8_LSW | | FP32bit-LSW | R/W | | 40045 |
| | Preset counter value of PulseCounter8 | | | | |
| Overflow | | Bit | R | | 40007 |
| | These bits aren't used | | | / | |
| | Pulse counter 8 overflow: 0=there isn't; 1=there is | | | / | |
| | Pulse counter 7 overflow: 0=there isn't; 1=there is | | | / | |
| | Pulse counter 6 overflow: 0=there isn't; 1=there is | | | / | |
| | Pulse counter 5 overflow: 0=there isn't; 1=there is | | | / | |
| | Pulse counter 4 overflow: 0=there isn't; 1=there is | | | / | |
| | Pulse counter 3 overflow: 0=there isn't; 1=there is | | | / | |
| | Pulse counter 2 overflow: 0=there isn't; 1=there is | | | / | |
| | Pulse counter 1 overflow: 0=there isn't; 1=there is | | | / | |

The «Input Status»-type registers used for ZC-24DI module are shown in the following table:

| Name | Range | Interpretation of register | R/W | Default | Address |
|------------|--------------------------------------|----------------------------|-----|---------|---------|
| State IN1 | 0-1 | Word | R | | 10001 |
| | IN1 state: 0=S1 open; 1=S1 closed | | | / | |
| State IN2 | 0-1 | Word | R | | 10002 |
| | IN2 state: 0=S2 open; 1=S2 closed | | | / | |
| State IN3 | 0-1 | Word | R | | 10003 |
| | IN3 state: 0=S3 open; 1=S3 closed | | | / | |
| State IN4 | 0-1 | Word | R | | 10004 |
| | IN4 state: 0=S4 open; 1=S4 closed | | | / | |
| State IN5 | 0-1 | Word | R | | 10005 |
| | IN5 state: 0=S5 open; 1=S5 closed | | | / | |
| State IN6 | 0-1 | | R | | 10006 |
| | IN6 state: 0=S6 open; 1=S6 closed | | | / | |
| State IN7 | 0-1 | | R | | 10007 |
| | IN7 state: 0=S7 open; 1=S7 closed | | | / | |
| State IN8 | 0-1 | | R | | 10008 |
| | IN8 state: 0=S8 open; 1=S8 closed | | | / | |
| State IN9 | 0-1 | | R | | 10009 |
| | IN9 state: 0=S9 open; 1=S9 closed | | | / | |
| State IN10 | 0-1 | | R | | 10010 |
| | IN10 state: 0=S10 open; 1=S10 closed | | | / | |
| State IN11 | 0-1 | Word | R | | 10011 |
| | IN11 state: 0=S11 open; 1=S11 closed | | | / | |
| State IN12 | 0-1 | Word | R | | 10012 |
| | IN12 state: 0=S12 open; 1=S12 closed | | | / | |
| State IN13 | 0-1 | Word | R | | 10013 |
| | IN13 state: 0=S13 open; 1=S13 closed | | | / | |
| State IN14 | 0-1 | Word | R | | 10014 |
| | IN14 state: 0=S14 open; 1=S14 closed | | | / | |
| State IN15 | 0-1 | Word | R | | 10015 |
| | IN15 state: 0=S15 open; 1=S15 closed | | | / | |
| State IN16 | 0-1 | Word | R | | 10016 |
| | IN16 state: 0=S16 open; 1=S16 closed | | | / | |
| State IN17 | 0-1 | Word | R | | 10017 |
| | IN17 state: 0=S17 open; 1=S17 closed | | | / | |
| State IN18 | 0-1 | Word | R | | 10018 |
| | IN18 state: 0=S18 open; 1=S18 closed | | | / | |
| State IN19 | 0-1 | Word | R | | 10019 |
| | IN19 state: 0=S19 open; 1=S19 closed | | | / | |
| State IN20 | 0-1 | Word | R | | 10020 |
| | IN20 state: 0=S20 open; 1=S20 closed | | | / | |
| State IN21 | 0-1 | Word | R | | 10021 |
| | IN21 state: 0=S21 open; 1=S21 closed | | | / | |
| State IN22 | 0-1 | Word | R | | 10022 |
| | IN22 state: 0=S22 open; 1=S22 closed | | | / | |
| State IN23 | 0-1 | Word | R | | 10023 |
| | IN23 state: 0=S23 open; 1=S23 closed | | | / | |
| State IN24 | 0-1 | Word | R | | 10024 |
| | IN24 state: 0=S24 open; 1=S24 closed | | | / | |

LEDs for signalling

In the front-side panel there are 28 LEDs and their state refers to important operating conditions of the module.

| LED | LED status | Meaning |
|------------|-------------------|--|
| PWR | Constant light | The power is on |
| FAIL | Blinking light | The module received a data packet through RS232 port |
| ERR (TX) | Constant light | Verify if the bus connection is corrected |
| | Blinking light | The module sent a data packet |
| RUN (RX) | Blinking light | The module received a data packet |
| | Constant light | Verify if the bus connection is corrected |
| 1-24 | Constant light | IN1-24 state equal to «1» |
| | No light | IN1-24 state equal to «0» (if the power is on) |

Easy-SETUP

To configure the Seneca Z-PC Line modules, it is possible to use Easy-SETUP software,

Free-downloadable from the www.seneca.it; the configuration can be performed by RS232 or RS485 bus communication.

Seneca Z-PC Line module: **ZC-24DI** (CANOpen)

In this chapter are described the features of ZC-24DI module, based on CANOpen protocol.

NOTE: “0x” means an exadecimal number interpretation.

CANOpen features

| TECHNICAL DATA | |
|-------------------------------|--|
| Baud rate | 20, 50, 125, 250, 500, 800, 1000 kbps |
| Counters nr/type | 8 (32bit) from input 1..8 |
| Max frequency for counters | 10 kHz |
| Typical ON/OFF delay | 1 ms (with filter disabled) |
| CANOpen TECHNICAL DATA | |
| NMT | slave |
| Node ID | Node guarding, heartbeat |
| Node ID | HW switch or software |
| Number of PDO | 5 TX |
| PDO modes | Event triggered, Sync (cyclic), Sync (acyclic) |
| PDO mapping | Variable |
| PDO linking | supported |
| Number of SDO | 1 server |
| Error message | yes |
| Supported application | Cia 301 v4.02 |
| Layer | Cia 401 v2.01 |

CANOpen TPDOs transmission type supported

| Object Value 0x180x Sub 2 | TRANSMISSION TYPE |
|----------------------------------|--------------------------|
| 0 | Synchronous - acyclic |
| From 1 to 240 | Synchronous - cyclic |
| 255 | Asynchronous |

CANOpen PDOs mapping

| OBJECTS FOR DEFAULT MAPPING | | | | |
|-----------------------------|---------------------------|-------------------------|--------|----------|
| PDO NR | COB-ID | MAPPED OBJECTS | INDEX | SUBINDEX |
| TPDO1 | 0x40000180 + NodeId | Digital input [1..8] | 0x6000 | 1 |
| | | Digital input [9..16] | 0x6000 | 2 |
| | | Digital input [17..24] | 0x6000 | 3 |
| | | Overflow counter [1..8] | 0x6000 | 4 |
| TPDO5 | 0x40000280 + NodeId | Counter 1 value | 0x2210 | 1 |
| | | Counter 2 value | 0x2210 | 2 |
| TPDO6 | 0x40000380 + NodeId | Counter 3 value | 0x2210 | 3 |
| | | Counter 4 value | 0x2210 | 4 |
| TPDO7 | 0x40000480 + NodeId | Counter 5 value | 0x2210 | 5 |
| | | Counter 6 value | 0x2210 | 6 |
| TPDO8 | 0x40000300 + NodeId | Counter 7 value | 0x2210 | 7 |
| | | Counter 8 value | 0x2210 | 8 |

Note that TPDO COB-ID must start with 0x4.

CANOpen emergency message

The Emergency message is composed by:

2 bytes of EEC (Emergency error code)

1 bytes of ER (Error register)

4 bytes MEF (Manufacturer error filled objects) (0x1002)

| EMERGENCY MESSAGE | | | | | | |
|-------------------|--------|--------|--------|--------|--------|--------|
| BYTE 0 | BYTE 1 | BYTE 2 | BYTE 3 | BYTE 4 | BYTE 5 | BYTE 6 |
| EER | | ER | MEF | | | |

| EEC | |
|--------|----------------------------------|
| Code | Description |
| 0x0000 | No error |
| 0x1000 | Generic error |
| 0x4201 | CPU temperature over T_HIGH_HIGH |
| 0x4202 | CPU temperature over T_HIGH |
| 0x4203 | CPU temperature under T_LOW |
| 0x8110 | Communication Can Overrun |
| 0x8120 | Error passive |
| 0x8130 | Life Guard error |
| 0x8140 | Recovered from bus off |
| 0xFF20 | CPU error |

| ER | | | | | | | |
|---------|-------|-------|-------------|---------------|-------|-------|-------------|
| BIT 7 | BIT 6 | BIT 5 | BIT 4 | BIT 3 | BIT 2 | BIT 1 | BIT 0 |
| Generic | 0 | 0 | temperature | communication | 0 | 0 | Manufacture |

Where bit equal to “0” means “no error”.

CANOpen manufacturer specific profile

If dip-switches are in “from memory” mode, the node address is selectable by **Object 0x2001**.

| NODE ADDRESS (Object 0x2001) | |
|------------------------------|--------------|
| Object value | Description |
| 0..127 | Node address |

If dip-switches are in “from memory” mode, the baud rate is selectable by **Object 0x2002**.

| BAUDRATE (Object 0x2002) | |
|--------------------------|-------------|
| Object value | Description |
| 1 | 20 kbit/s |
| 2 | 50 kbit/s |
| 3 | 125 kbit/s |
| 4 | 250 kbit/s |
| 5 | 500 kbit/s |
| 6 | 800 kbit/s |
| 7 | 1 Mbit/s |

Object 0x2030 can be used to monitor the CPU temperature.

| CPU TEMPERATURE (Object 0x2030) | |
|---------------------------------|---|
| Subindex | Description |
| 1 | Actual temperature [°C/10] |
| 2 | Temperature for HOT STOP ERROR [°C/10] 95.0°C |
| 3 | Temperature for HOT ERROR [°C/10] 90.0°C |
| 4 | Temperature for COLD ERROR [°C/10] -25.0°C |

The HOT STOP temperature sends in pre-operational the station.

The HOT ERROR and the COLD ERROR temperature sends the Emergency Object.

The Object is Read Only.

Object 0x2051 is used to send commands to the station module.

| CPU COMMAND (Object 0x2051) | |
|-----------------------------|--|
| Command code | Description |
| 0x5C0n | Force the preset value (object 0x2211) for counter n |
| 0x5D0n | Force the reset for counter n |
| 0x5E0n | Force the overflow reset (object 0x6000 sub 4) |

Object 0x2200 is used to customize the input filter.

| FILTER PARAMETERS (Object 0x2200) | |
|-----------------------------------|---|
| Subindex | Description |
| 1 | Samples number for filter (default 40) |
| 2 | Counter threshold for high level (default 20) |
| 3 | Counter threshold for low level (default 20) |

For a high level sample the filter counter is incremented, otherwise for a low level the filter counter is decremented.

When the filter counter is greater or equal to subindex2, the input is stated "high".

When the filter counter is lower or equal to subindex3, the input is stated "low".

Between subindex2 and subindex3, no state is asserted (dead zone).

Note that the filter can be disabled by selecting:

Subindex1=1

Subindex2=0

Subindex3=0

Object 0x2210 stores the values of the 8 counters in 32bit format.

| DIGITAL COUNTERS (Object 0x2210) | |
|----------------------------------|-----------------|
| Subindex | Description |
| 1 | Counter 1 value |
| 2 | Counter 2 value |
| 3 | Counter 3 value |
| 4 | Counter 4 value |
| 5 | Counter 5 value |
| 6 | Counter 6 value |
| 7 | Counter 7 value |
| 8 | Counter 8 value |

DIP-SWITCH configuration

| BAUD-RATE (Dip-Switches: SW1) | | | | | | | |
|--|---------------------------|---------------------|---|---|---|----|---|
| 1 | 2 | 3 | Meaning | | | | |
| | | | Only Baud-Rate is acquired from memory(EEPROM) | | | | |
| | | ● | 20 kbps | | | | |
| | ● | | 50 kbps | | | | |
| | ● | ● | 125 kbps | | | | |
| ● | | | 250 kbps | | | | |
| ● | | ● | 500 kbps | | | | |
| ● | ● | | 800 kbps | | | | |
| ● | ● | ● | 1 Mbps | | | | |
| ADDRESS (Dip-Switches: SW1) | | | | | | | |
| 4 | 5 | 6 | 7 | 8 | 9 | 10 | Meaning |
| | | | | | | | Only address is acquired from memory(EEPROM) |
| | | | | | | ● | Address=1 |
| | | | | | ● | | Address=2 |
| | | | | | ● | ● | Address=3 |
| | | | | ● | | | Address=4 |
| | | | | ● | | ● | Address=5 |
| X | X | X | X | X | X | X | |
| ● | ● | ● | ● | ● | ● | ● | Address=127 |
| RS485 TERMINATOR (Dip-Switches: SW3) | | | | | | | |
| 1 | Meaning | | | | | | |
| | RS485 terminator disabled | | | | | | |
| ● | RS485 terminator enabled | | | | | | |
| COMMUNICATION PROTOCOL (Dip-Switch: SW2 and SW4) | | | | | | | |
| SW2 | SW4 | | | | | | |
| 1 | 1 | | | | | | |
| | | Protocol is ModBUS | | | | | |
| ● | ● | Protocol is CANOPEN | | | | | |

CANOpen LED description

| SERVICE (DIAGNOSTIC) LED DESCRIPTION | | |
|--------------------------------------|----------------|--|
| LED | LED status | Meaning |
| RUN | Blinking light | Pre-operational mode |
| | Single flash | Stop mode |
| | ON | Operational mode |
| ERROR | Single flash | At least one error counter has reached or exceed the warning level |
| | Double flash | Guard event |
| | Triple flash | The SYNC has not received within the configured communication cycle timeout period |
| | ON | The CAN controller is bus off |
| | OFF | No error |
| FAIL | ON Blinking | Data receiving from RS232 |
| POWER | ON | Power supply |
| INPUT LED DESCRIPTION | | |
| LED | LED status | Meaning |
| 1-8 | ON | Input [1..8] is high |
| | OFF | Input [1..8] is low |
| 9-24 | ON | Input [9..24] is high |
| | OFF | Input [9..24] is low |

CANOpen digital input management

Object 0x6003 is used for input filter configuration.

| FILTER CONSTANT INPUT (Object 0x6003) | |
|---------------------------------------|---|
| Subindex | Description |
| 1 | Filter enabled for input [1..8] |
| 2 | Filter enabled for input [9..16] read only |
| 3 | Filter enabled for input [17..24] read only |

Object 0x6005 is used for Interrupt Enable:

If the value is “1” the station can generate a synchronous TxPDO (DEFAULT setting).

If the value is “0” the station can't generate a synchronous TxPDO.

Object 0x6007 is used as Digital Interrupt Mask Low to High.

| INTERRUPT MASK LOW TO HIGH (Object 0x6007) | |
|--|--|
| Subindex | Description |
| 1 | Interrupt mask on rising edge input [1..8] |
| 2 | Interrupt mask on rising edge input [9..16] |
| 3 | Interrupt mask on rising edge input [17..24] |
| 4 | Interrupt mask for counters |

For subindex from 1 to 3 if value is “1”, the generation of TxPDO on rising edge is enabled.

If subindex 4 value is “1”, the generation of TxPDO on all 8 counters overflows is enabled.

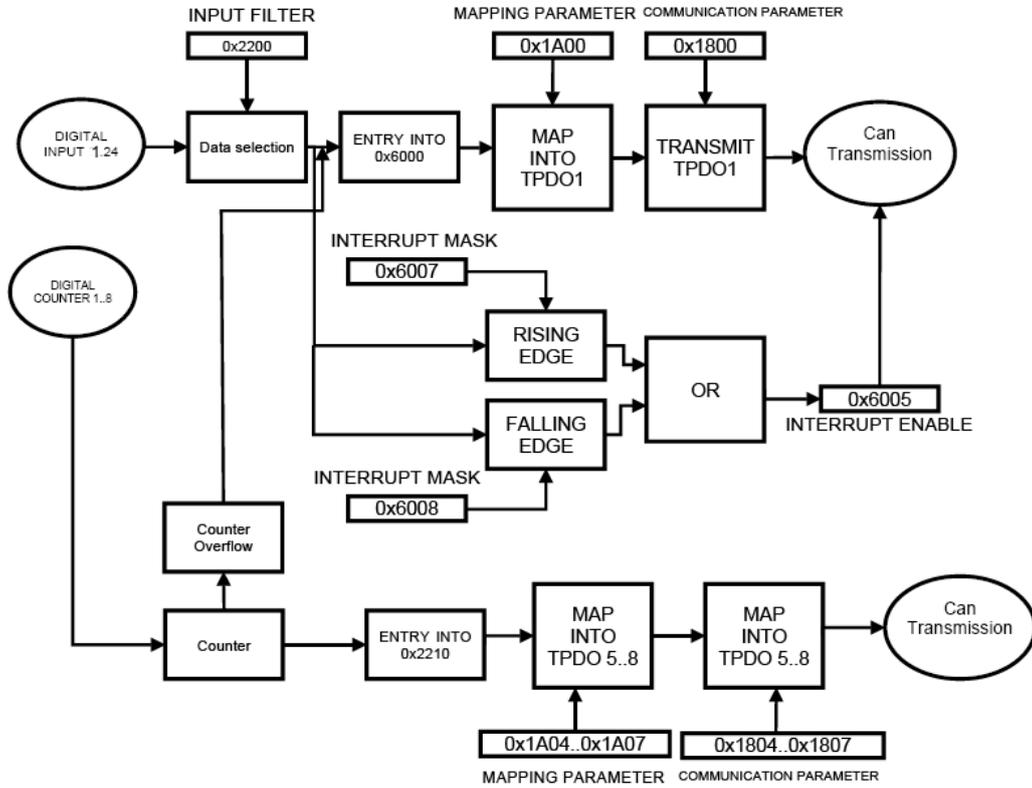
Object 0x6008 is used as Digital Interrupt Mask High to Low.

| INTERRUPT MASK HIGH TO LOW (Object 0x6008) | |
|--|---|
| Subindex | Description |
| 1 | Interrupt mask on falling edge input [1..8] |
| 2 | Interrupt mask on falling edge input [9..16] |
| 3 | Interrupt mask on falling edge input [17..24] |

For subindex from 1 to 3, if value is “1” the generation of TxPDO on falling edge is enable.

CANOpen functional diagram

counter mode ON (subindex 1 Object 0x6003="0")



CANOpen Object dictionary

| COMMUNICATION PROFILE AREA | | | | | | |
|-----------------------------------|-----------|--|--|----------------|--------|------------|
| INDEX | SUB INDEX | NAME | DESCRIPTION | TYPE | ACCESS | DEFAULT |
| 0x1000 | 0 | Device type | (profile 401=0x191) | UNSIGNED 32 | RO | 0x00010191 |
| 0x1001 | 0 | Error register | Error register (DS401) | UNSIGNED 8 | RO | 0 |
| 0x1002 | 0 | Manufacturer Status register | Status register | UNSIGNED 32 | RO | 0 |
| 0x1005 | 0 | SYNC COB-ID | The device consumes the SYNC message | UNSIGNED 32 | RW | 0x00000080 |
| 0x1006 | 0 | Comm. window lenght | Sync interval [us] | UNSIGNED 32 | RW | 0 |
| 0x1007 | 0 | Synchronous window lenght | The window [us] for the PDO transmission after the SYNC | UNSIGNED 32 | RW | 0 |
| 0x1008 | 0 | Manufacturer Device name | Device name | VISIBLE STRING | RO | "ZC-24DI" |
| 0x1009 | 0 | Manufacturer HW version | Hardware version | VISIBLE STRING | RO | "SC000000" |
| 0x100A | 0 | Manufacturer SW version | Software version | VISIBLE STRING | RO | "SW001171" |
| 0x100C | 0 | Guard Time | [ms] | UNSIGNED 16 | RW | 0 |
| 0x100D | 0 | Life time factor | Max delay between two guarding telegrams= Guard_Time· Life_Time_Factor | UNSIGNED 8 | RW | 0 |
| 0x1010 | 0 | Store parameters/ number of mapped object | Max subindex number | UNSIGNED 8 | RO | 4 |
| | 1 | Save all parameters | Store not volatile parameters (write in ASCII "save" for store process MSB 0x65766173 LSB) | UNSIGNED 32 | RW | 1 |
| | 2 | Save communication parameters | Store not volatile parameters (write in ASCII "save" for store process MSB 0x65766173 LSB) | UNSIGNED 32 | RW | 1 |
| | 3 | Save application parameters | Store not volatile parameters | UNSIGNED 32 | RW | 1 |
| | 4 | Save manufactures parameters | Store not volatile parameters | UNSIGNED 32 | RW | 1 |

| | | | | | | |
|--------|---|---|--|-------------|----|-------------------------|
| 0x1011 | 0 | Restore default/ number of mapped object | Max subindex number | UNSIGNED 8 | RO | 4 |
| | 1 | Restore all parameters | Restore not volatile parameters (write in ASCII "load" for store process MSB 0x64616F6C LSB) | UNSIGNED 32 | RW | 0 |
| | 2 | Restore communication parameters | Restore not volatile parameters (write in ASCII "load" for store process MSB 0x64616F6C LSB) | UNSIGNED 32 | RW | 0 |
| | 3 | Restore application parameters | Restore not volatile parameters (write in ASCII "load" for store process MSB 0x64616F6C LSB) | UNSIGNED 32 | RW | 0 |
| | 4 | Restore Manufactures parameters | Restore not volatile parameters (write in ASCII "load" for store process MSB 0x64616F6C LSB) | UNSIGNED 32 | RW | 0 |
| 0x1014 | 0 | COB-ID emergency Object | | UNSIGNED 32 | RO | \$NODEID+ 0x80 |
| 0x1017 | 0 | Heartbeat producer time | Time (ms) 0x0000=there is not heartbeat service | UNSIGNED 16 | RW | 0 |
| 0x1018 | 0 | Identity object/ number of mapped object | Max subindex number | UNSIGNED 8 | RO | 4 |
| | 1 | Vendor ID | Seneca srl | UNSIGNED 32 | RO | 0x00000249 |
| | 2 | Product code | ZC-24DI Machine ID Code | UNSIGNED 32 | RO | 0x00000020 |
| | 3 | Revision number | | UNSIGNED 32 | RO | 0 |
| | 4 | Serial number | | UNSIGNED 32 | RO | 0 |
| 0x1200 | 0 | 1 st SDO port/ number of mapped object | Max subindex number | UNSIGNED 8 | RO | 2 |
| | 1 | COB-ID SDO Client-> Server | COB-ID of receive SDO | UNSIGNED 32 | RO | \$NODEID+ 0x600 |
| | 2 | COB-ID SDO Server-> Client | COB-ID of transmit SDO | UNSIGNED 32 | RO | \$NODEID+ 0x580 |
| 0x1800 | 0 | 1 st transmit PDO parameters /number of mapped object | Max subindex number | UNSIGNED 8 | RO | 3 |
| | 1 | COB-ID used by PDO | COB-ID of TPDO1 | UNSIGNED 32 | RW | \$NODEID+ 0x40000180 |
| | 2 | Transmission type | Transmission type forTxPDO1 0x00=synchronous- acyclic | UNSIGNED 8 | RW | 0xFF |

| | | | | | | |
|--------|---|--|---|-------------|----|-------------------------|
| | | | 0x01 to 0xF0 =synchronous- cyclic 0xFF=asynchronous | | | |
| | 3 | Inhibit time | Min delay for the next PDO (ms/10) | UNSIGNED 16 | RW | 0x0000 |
| 0x1804 | 0 | 5th transmit PDO parameters /number of mapped object | Max subindex number | UNSIGNED 8 | RO | 3 |
| | 1 | COB-ID used by PDO | COB-ID of TPDO5 | UNSIGNED 32 | RW | \$NODEID+ 0x40000280 |
| | 2 | Transmission type | Transmission type forTxPDO5 0x00=synchronous-acyclic 0x01 to 0xF0 =synchronous- cyclic 0xFF=asynchronous | UNSIGNED 8 | RW | 0x01 |
| | 3 | Inhibit time | Min delay for the next PDO (ms/10) | UNSIGNED 16 | RW | 0x0000 |
| 0x1805 | 0 | 6th transmit PDO parameters /number of mapped object | Max subindex number | UNSIGNED 8 | RO | 3 |
| | 1 | COB-ID used by PDO | COB-ID of TPDO6 | UNSIGNED 32 | RW | \$NODEID+ 0x40000380 |
| | 2 | Transmission type | Transmission type forTxPDO6 0x00=synchronous-acyclic 0x01 to 0xF0 =synchronous- cyclic 0xFF=asynchronous | UNSIGNED 8 | RW | 0x01 |
| | 3 | Inhibit time | Min delay for the next PDO (ms/10) | UNSIGNED 16 | RW | 0x0000 |
| 0x1806 | 0 | 7th transmit PDO parameters /number of mapped object | Max subindex number | UNSIGNED 8 | RO | 3 |
| | 1 | COB-ID used by PDO | COB-ID of TPDO7 | UNSIGNED 32 | RW | \$NODEID+ 0x40000480 |
| | 2 | Transmission type | Transmission type forTxPDO7 0x00=synchronous-acyclic 0x01 to 0xF0 =synchronous- cyclic 0xFF=asynchronous | UNSIGNED 8 | RW | 0x01 |
| | 3 | Inhibit time | Min delay for the next PDO (ms/10) | UNSIGNED 16 | RW | 0x0000 |

| | | | | | | |
|--------|---|---|---|-------------|----|--|
| 0x1807 | 0 | 8th transmit PDO parameters /number of mapped object | Max subindex number | UNSIGNED 8 | RO | 3 |
| | 1 | COB-ID used by PDO | COB-ID of TPDO8 | UNSIGNED 32 | RW | \$NODEID+ 0x40000300 |
| | 2 | Transmission type | Transmission type forTxPDO8 0x00=synchronous-acyclic 0x01 to 0xF0 =synchronous- cyclic 0xFF=asynchronous | UNSIGNED 8 | RW | 0x01 |
| | 3 | Inhibit time | Min delay for the next PDO (ms/10) | UNSIGNED 16 | RW | 0x0000 |
| 0x1A00 | 0 | 1 st Transmit PDO mapping parameter/ number of mapped object | Max subindex number | UNSIGNED 8 | RW | 4 |
| | 1 | 1 st object to be mapped | First object (default: input 1..8) | UNSIGNED 32 | RW | 0x60000108 Object=0x6000 Subindex=1 Length=8bit |
| | 2 | 2nd object to be mapped | Second object (default: input 9..16) | UNSIGNED 32 | RW | 0x60000208 Object=0x6000 Subindex=2 Length=8bit |
| | 3 | 3rd object to be mapped | Third object (default: input 17..24) | UNSIGNED 32 | RW | 0x60000308 Object=0x6000 Subindex=3 Length=8bit |
| | 4 | 4th object to be mapped | Fourth object (default: counter overflow) | UNSIGNED 32 | RW | 0x60000408 Object=0x6000 Subindex=4 Length=8bit |
| 0x1A04 | 0 | 5th Transmit PDO mapping parameter/ number of mapped object | Max subindex number | UNSIGNED 8 | RW | 2 |
| | 1 | 1 st object to be mapped | First object (default: counter 1) | UNSIGNED 32 | RW | 0x22100120 Object=0x2210 Subindex=1 Length=32bit |
| | 2 | 2nd object to be mapped | Second object (default: counter 2) | UNSIGNED 32 | RW | 0x22100220 Object=0x2210 Subindex=2 Length= 32bit |

| | | | | | | |
|--------|---|---|------------------------------------|-------------|----|--|
| 0x1A05 | 0 | 6th Transmit PDO mapping parameter/ number of mapped object | Max subindex number | UNSIGNED 8 | RW | 2 |
| | 1 | 1 st object to be mapped | First object (default: counter 3) | UNSIGNED 32 | RW | 0x22100320 Object=0x2210 Subindex=3 Length=32bit |
| | 2 | 2nd object to be mapped | Second object (default: counter 4) | UNSIGNED 32 | RW | 0x22100420 Object=0x2210 Subindex=4 Length= 32bit |
| 0x1A06 | 0 | 7th Transmit PDO mapping parameter/ number of mapped object | Max subindex number | UNSIGNED 8 | RW | 2 |
| | 1 | 1 st object to be mapped | First object (default: counter 5) | UNSIGNED 32 | RW | 0x22100520 Object=0x2210 Subindex=5 Length=32bit |
| | 2 | 2nd object to be mapped | Second object (default: counter 6) | UNSIGNED 32 | RW | 0x22100620 Object=0x2210 Subindex=6 Length= 32bit |
| 0x1A07 | 0 | 8th Transmit PDO mapping parameter/ number of mapped object | Max subindex number | UNSIGNED 8 | RW | 2 |
| | 1 | 1 st object to be mapped | First object (default: counter 7) | UNSIGNED 32 | RW | 0x22100720 Object=0x2210 Subindex=7 Length=32bit |
| | 2 | 2nd object to be mapped | Second object (default: counter 8) | UNSIGNED 32 | RW | 0x22100820 Object=0x2210 Subindex=8 Length= 32bit |

MANUFACTURER PROFILE AREA

| INDEX | SUB INDEX | NAME | DESCRIPTION | TYPE | ACCESS | DEFAULT |
|--------|-----------|----------------|--|------------|--------|----------|
| 0x2001 | 0 | Module address | Station address (only if dip switch 4,5,6,7,8,9,10 are OFF) | UNSIGNED 8 | RW | 0x7F=127 |
| 0x2002 | 0 | Baudrate | Station Baudrate (only if dip switch 1,2,3 are OFF) 1=20kbps 2=50kbps 3=125kbps 4=250kbps 5=500kbps 6=800kbps 7=1Mbps | UNSIGNED 8 | RW | 0x01 |

| | | | | | | |
|--------|---|--|---|-------------|----|------|
| 0x2003 | 0 | Master firmware code | | UNSIGNED 16 | RO | 1179 |
| 0x2030 | 0 | Device temperature/ number of parameters | Max subindex number | UNSIGNED 8 | RO | 4 |
| | 1 | Internal temperature | Station internal temperature [°C/10] | INTEGER 16 | RO | 0 |
| | 2 | Hi Hi temperature | Critical hot temperature (all operations stop) [°C/10] | INTEGER 16 | RO | 950 |
| | 3 | Hi temperature | Warning for too hot temperature [°C/10] | INTEGER 16 | RO | 900 |
| | 4 | Low temperature | Critical low temperature (all operations stop) [°C/10] | INTEGER 16 | RO | -250 |
| 0x2051 | 0 | Command | Command to execute Supported commands: 0x5Cnn force preset for counter mask nn 0x5Dnn force reset for counter mask nn 0x5Enn force overflow for counter mask nn | UNSIGNED 16 | RW | 0 |
| 0x2052 | 0 | Aux command | reserved | UNSIGNED 16 | RW | 0 |
| 0x2200 | 0 | Input filter parameter/ number of parameters | Max subindex number | UNSIGNED 8 | RO | 3 |
| | 1 | Filter lenght | Number of samples to evaluate | UNSIGNED 8 | RW | 40 |
| | 2 | Counter threshold for high level | If counter >= threshold_high input is stated "high" | UNSIGNED 8 | RW | 20 |
| | 3 | Counter threshold for low level | If counter <= threshold_low input is stated "low" | UNSIGNED 8 | RW | 20 |
| 0x2210 | 0 | Input counters/ number of counter | Max subindex number | UNSIGNED 8 | RO | 0x8 |
| | 1 | Counter 1 value | | UNSIGNED 32 | RO | 0 |

| | | | | | | |
|--------|---|--|--|----------------|----|-----|
| | 2 | Counter 2 value | | UNSIGNED 32 | RO | 0 |
| | 3 | Counter 3 value | | UNSIGNED 32 | RO | 0 |
| | 4 | Counter 4 value | | UNSIGNED 32 | RO | 0 |
| | 5 | Counter 5 value | | UNSIGNED 32 | RO | 0 |
| | 6 | Counter 6 value | | UNSIGNED 32 | RO | 0 |
| | 7 | Counter 7 value | | UNSIGNED 32 | RO | 0 |
| | 8 | Counter 8 value | | UNSIGNED 32 | RO | 0 |
| 0x2211 | 0 | Preset for input counters/ number of counters | | UNSIGNED 8 | RO | 0x8 |
| | 1 | Counter 1 preset value | | UNSIGNED 32 | RW | 0 |
| | 2 | Counter 2 preset value | | UNSIGNED 32 | RW | 0 |
| | 3 | Counter 3 preset value | | UNSIGNED 32 | RW | 0 |
| | 4 | Counter 4 preset value | | UNSIGNED 32 | RW | 0 |
| | 5 | Counter 5 preset value | | UNSIGNED 32 | RW | 0 |
| | 6 | Counter 6 preset value | | UNSIGNED 32 | RW | 0 |
| | 7 | Counter 7 preset value | | UNSIGNED 32 | RW | 0 |
| | 8 | Counter 8 preset value | | UNSIGNED 32 | RW | 0 |

STANDARD DEVICE PROFILE AREA

| INDEX | SUB INDEX | NAME | DESCRIPTION | TYPE | ACCESS | DEFAULT |
|--------|-----------|---|--------------------------------|---------------|--------|---------|
| 0x6000 | 0 | 8 bit digital input counter1 overflow/ number of input 8 bit | Max subindex number | UNSIGNED 8 | RO | 4 |
| | 1 | Input [1..8] value | Read input [1..8] value | UNSIGNED 8 | RO | 0 |
| | 2 | Input [9..16] value | Read input [9..16] value | UNSIGNED 8 | RO | 0 |
| | 3 | Input [17..24] value | Read input [17..24] value | UNSIGNED 8 | RO | 0 |
| | 4 | Counter [1..8] overflow | Overflow status counter [1..8] | UNSIGNED 8 | RO | 0 |
| 0x6003 | 0 | Filter mask enable/ number of input 8 bit | Max subindex number | UNSIGNED 8 | RO | 3 |

| | | | | | | |
|--------|---|--|---|---------------|----|------|
| | 1 | Input [1..8] filter mask enable | Input [1..8] Filter enable Mask (only 0x00 or 0xFF allowed) 0x00 = Filter disabled (and Counters 1..8 Enabled) 0xFF = Filter enabled (and Counters 1..8 Disabled) | UNSIGNED 8 | RW | 0xFF |
| | 2 | Input [9..16] filter mask enable | Filter activation for inputs IN9-IN16 using a bit interpretation to mask the inputs: are always deactivated | UNSIGNED 8 | RO | 0x00 |
| | 3 | Input [17..24] filter mask enable | Filter activation for inputs IN17-IN24 using a bit interpretation to mask the inputs: are always deactivated | UNSIGNED 8 | RO | 0x00 |
| 0x6005 | 0 | Global interrupt enabled | 0=TxPDO asynchronous disabled 1=TxPDO asynchronous enabled | UNSIGNED 8 | RW | 1 |
| 0x6007 | 0 | Interrupt mask Low to High/number of input | Max subindex number | UNSIGNED 8 | RO | 4 |
| | 1 | Mask interrupt input [1..8] | Input [1..8] rising interrupt mask enable Mask bit0=rising interrupt disabled Mask bit1=rising interrupt enabled | UNSIGNED 8 | RW | 0xFF |
| | 2 | Mask interrupt input [9..16] | Input [9..16] rising interrupt mask enable Mask bit0=rising interrupt disabled Mask bit1=rising interrupt enabled | UNSIGNED 8 | RW | 0xFF |
| | 3 | Mask interrupt input [17..24] | Input [17..24] rising interrupt mask enable Mask bit0=rising interrupt disabled Mask bit1=rising interrupt enabled | UNSIGNED 8 | RW | 0xFF |

| | | | | | | |
|--------|----|--|---|---------------|----|------|
| | 4 | Mask interrupt counter overflow | Counter [1..8] rising interrupt mask enable Mask bit0=rising interrupt disabled Mask bit1=rising interrupt enabled | UNSIGNED 8 | RW | 0x00 |
| 0x6008 | 0 | Interrupt mask High to Low/number of input | Max subindex number | UNSIGNED 8 | RO | 3 |
| | 1 | Mask interrupt input [1..8] | Input [1..8] falling interrupt mask enable Mask bit0= falling interrupt disabled Mask bit1=rising interrupt enabled | UNSIGNED 8 | RW | 0xFF |
| | 2 | Mask interrupt input [9..16] | Input [9..16] falling interrupt mask enable Mask bit0= falling interrupt disabled Mask bit1= falling interrupt enabled | UNSIGNED 8 | RW | 0xFF |
| | 3 | Mask interrupt input [17..24] | Input [17..24] falling interrupt mask enable Mask bit0= falling interrupt disabled Mask bit1= falling interrupt enabled | UNSIGNED 8 | RW | 0xFF |
| 0x6020 | 0 | Read input 1 bit/ number of input bit | Max subindex number | UNSIGNED 8 | RO | 24 |
| | 1 | Input 1 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 2 | Input 2 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 3 | Input 3 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 4 | Input 4 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 5 | Input 5 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 6 | Input 6 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 7 | Input 7 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 8 | Input 8 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 9 | Input 9 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 10 | Input 10 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 11 | Input 11 value | 0=input is "low" | BOOLEAN | RO | |

| | | | | | | |
|--|----|----------------|---------------------------------------|---------|----|--|
| | | | 1=input is "high" | | | |
| | 12 | Input 12 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 13 | Input 13 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 14 | Input 14 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 15 | Input 15 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 16 | Input 16 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 17 | Input 17 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 18 | Input 18 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 19 | Input 19 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 20 | Input 20 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 21 | Input 21 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 22 | Input 22 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 23 | Input 23 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |
| | 24 | Input 24 value | 0=input is "low" 1=input is "high" | BOOLEAN | RO | |